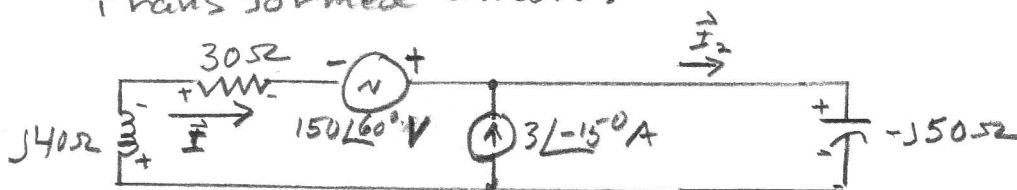


Find the steady state value of $i(t)$.

$$j\omega L = j(1000)(.04) = \underline{j40\Omega} \quad \frac{1}{j\omega C} = \frac{1}{j(1000)(20 \times 10^{-6})} = \underline{-j50\Omega}$$

Transformed circuit:



$$\text{KVL: } j40\vec{I} + 30\vec{I} - 150\angle 60^\circ + (-j50)\vec{I}_2 = 0$$

$$\text{KCL: } -\vec{I} - 3\angle -15^\circ + \vec{I}_2 = 0$$

$$\therefore \vec{I}_2 = \vec{I} + 3\angle -15^\circ$$

Substituting into KVL:

$$j40\vec{I} + 30\vec{I} - 150\angle 60^\circ - j50(\vec{I} + 3\angle -15^\circ) = 0$$

$$j40\vec{I} + 30\vec{I} - 150\angle 60^\circ - j50\vec{I} - j150\angle -15^\circ = 0$$

$$\vec{I}(30 + j40 - j50) = 150\angle 60^\circ + j150\angle -15^\circ \quad (j = 1\angle 90^\circ)$$

$$\vec{I} = \frac{150\angle 60^\circ + 150\angle 75^\circ}{30 - j10} = \frac{(175 + j29.9) + (38.8 + j144.9)}{30 - j10}$$

$$= \frac{113.8 + j274.8}{30 - j10} = \frac{297.4\angle 67.5^\circ}{31.6\angle -18.3^\circ} = 9.41\angle 85.8^\circ \text{ A}$$

Transforming back to time domain:

$$\underline{i(t) = 9.41 \cos(1000t + 85.8^\circ) \text{ A}}$$